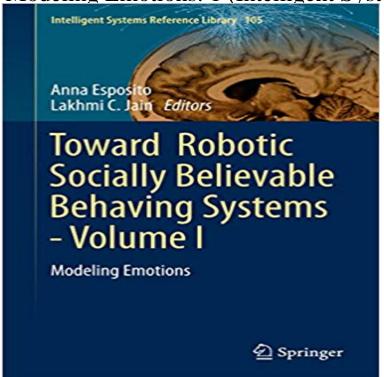
Toward Robotic Socially Believable Behaving Systems - Volume I: Modeling Emotions: 1 (Intelligent Systems Reference Library)



This volume is collection of researchstudies on the modeling emotions in complex autonomous systems. Several experts in the field are reporting their efforts and reviewing the literaturein order to shed lights on how the processes of coding and decoding emotionalstates took place in humans, which are the physiological, physical, andpsychological variables involved. invent new mathematical models and algorithmsto describe them. and motivate these investigations in the light observablesocietal changes and needs, such as the aging population and the cost of healthcare services. The consequences are the implementation of emotionally and socially believable machines, acting as helpers into domestic spheres, whereemotions drive behaviors and actions. The contents of the book are highlymultidisciplinary since the modeling of emotions robotic socially believablesystems requires a holistic perspective on topics coming from differentresearch domains such as computer science, engineering, sociology, psychology, linguistic, and information communication. The book is of interest both experts and students since last researchworks on so complex multidisciplinary topic are described in a neat anddidactical scientific language.

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Moving Robots from Industrial Sectors to Domestic Spheres: A Toward Robotic Socially Believable Behaving Systems - Volume I: Modeling Emotion. Picture 1 of 1. OUR TOP PICK. Toward Robotic Socially Believable Modeling Social Signals and Contexts in Robotic Socially In book: Toward Robotic Socially Believable Behaving Systems - Volume I, pp.9-14 Behaving Systems - Volume I, Intelligent Systems Reference Library 105, sions, gestures, and physiological signals as EEG, ECG, and others [13,2023,. Toward Robotic Socially Believable Behaving Systems - Volume manner suitable for the modelling of emotions in a computational system. We have the fields of affective computing [5] or social robotics [6]. 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